

Review

Thm. Let X be a Hilbert space, $T \in L(X)$ is a self-adjoint compact operator. Denote $\dim \operatorname{Im} T = N \in \mathbb{N} \cup \{\infty\}$

- $\exists$ eigenvalues $\{\lambda_n\}_{n=1}^N \subset \mathbb{R}$ of T and eigenvectors $\{p_n\}_{n=1}^N$ of T ($(p_i, p_j) = \delta_{ij}$).
- If $N = \infty$, then $\lambda_n \rightarrow 0$ ($n \rightarrow \infty$)

$$X = \ker T \oplus \ker T^\perp = \ker T \oplus \left(\bigoplus_{n=1}^N \operatorname{Span}(p_n) \right).$$

$$\forall x \in X, \quad T x = \sum_{k=1}^N \lambda_k (x, p_k) p_k$$

$$\parallel$$

$$u + \sum_{k=1}^N (x, p_k) p_k$$

$\uparrow$
 $\ker T$

- Let $\lambda \neq 0$ be an eigenvalue of T , then $\exists n \geq 1$ s.t. $\lambda_n = \lambda$ and $I(\lambda) = \{n \geq 1 : \lambda_n = \lambda\}$ is finite (and $\ker(\lambda \operatorname{Id} - T) = \operatorname{Span}(p_n)_{n \in I(\lambda)}$ is f.d.)

Setting $X/\mathbb{C}$ is a Banach space, $T \in L(X)$ a compact operator.

$$\sigma(T) := \{ \lambda \in \mathbb{C} : \lambda \operatorname{Id} - T \text{ is NOT invertible} \}$$

... $\lambda = 0$... $\lambda = \lambda_1, \dots, \lambda_N$... $\lambda = 0$...

$\sigma(T) := \{ \lambda \in \mathbb{C} : \lambda I - T \text{ is not invertible} \}$

$$\sigma_p(T) := \{ \lambda \in \mathbb{C} : \lambda I - T \text{ is not injective} \} \\ = \ker(\lambda I - T)$$

$\rho(T) := \mathbb{C} \setminus \sigma(T)$ the resolvent set of T .

Thm. • $\lim_{n \rightarrow \infty} \|T^n\|^{\frac{1}{n}}$ exists and

$$\lim_{n \rightarrow \infty} \|T^n\|^{\frac{1}{n}} = \inf_n \|T^n\|^{\frac{1}{n}}$$

denote $r(T) := \lim_{n \rightarrow \infty} \|T^n\|^{\frac{1}{n}}$ (the spectrum radius of T)

② $\sigma(T)$ is non-empty and compact in $\mathbb{C}$.

$$[\sigma(T) \subseteq \{ \lambda \in \mathbb{C} : |\lambda| \leq r(T) \}]$$

$\Downarrow$
① $\rho(T)$ is open

Proof • [Hint $n = q(n)n_0 + r(n)$ ($0 \leq r(n) \leq n_0 - 1$)

denote $a = \inf_n \|T_n\|^{\frac{1}{n}}$, $\forall \varepsilon > 0, \exists n_0$ s.t. $a + \varepsilon > \|T_{n_0}\|^{\frac{1}{n_0}}$

$$\|T^n\|^{\frac{1}{n}} = \|T^{q(n)n_0 + r(n)}\|^{\frac{1}{n}} \\ \leq \|T\|^{\frac{n_0 q(n)}{n}} \cdot \|T\|^{\frac{r(n)}{n}} \xrightarrow{\downarrow 1} 1$$

($\|AB\| \leq \|A\| \cdot \|B\|$)

$$\Rightarrow \limsup_{n \rightarrow \infty} \|T^n\|^{\frac{1}{n}} \leq \|T^{n_0}\|^{\frac{1}{n_0}} < a + \varepsilon = \inf_n \|T_n\|^{\frac{1}{n}} + \varepsilon \\ \Rightarrow \limsup_{n \rightarrow \infty} \|T^n\|^{\frac{1}{n}} \leq \inf_n \|T_n\|^{\frac{1}{n}} \leq \liminf_{n \rightarrow \infty} \|T_n\|^{\frac{1}{n}} \leq \limsup_{n \rightarrow \infty} \|T_n\|^{\frac{1}{n}}$$

• Take $\lambda_0 \in \rho(T)$, $h \in \mathbb{C}$

$$(\lambda_0 + h)Id - T = (\lambda_0 Id - T) + \underbrace{hId}_{\text{invertible}}$$

$$\rho(T) = \left\{ \lambda \in \mathbb{C} : \lambda Id - T \text{ is invertible} \right\}$$

FACT. $K: X \rightarrow X$ invertible

$\Rightarrow K - A$ is invertible if $\|K^{-1}A\| < 1$

$$(K - A)^{-1} = (K(Id - K^{-1}A))^{-1} = \left(\sum_{i=0}^{\infty} (K^{-1}A)^i \right) K^{-1}$$

$$(1-x)^{-1} = 1 + x + x^2 + \dots = 1 \quad \text{if } |x| < 1$$

Take $|h| < \frac{1}{\|\lambda_0 Id - T\|^{-1}}$. then $\lambda_0 + h \in \rho(T)$. $\square$

• CLAIM. $\sigma(T) \subseteq \overline{D(0, \|T\|)}$

Only need to show that $\lambda \in \mathbb{C}, |\lambda| > \|T\|$ then $\lambda \in \rho(T) \Rightarrow \lambda Id - T$ is invertible

$$(\lambda Id - T) = \lambda (Id - \lambda^{-1}T) \quad (|\lambda| > \|T\| \Rightarrow \|\lambda^{-1}T\| < 1)$$

$\downarrow$
invertible $\Rightarrow \lambda \in \rho(T)$ $\square$

$\Rightarrow \sigma(T)$ compact.

(In fact, $\sigma(T) \subseteq \overline{D(0, r(T))}$ (Exer.))

• Take a ^{bdd.} linear functional $\xi \in L(X)^*$

$$\varphi: \rho(T) \rightarrow \mathbb{C}$$

$$\lambda \mapsto (\lambda Id - T)^{-1} \xrightarrow{\xi} \xi((\lambda Id - T)^{-1})$$

$$\lambda \mapsto \underbrace{(\lambda \text{Id} - T)^{-1}}_{\substack{\rho(x) \\ \text{operator-valued holomorphic function}}} \xrightarrow{3} \xi[(\lambda \text{Id} - T)^{-1}]$$

CLAIM. φ is holomorphic.

Take $\lambda_0 \in \rho(T)$, $|h| < \|(\lambda_0 \text{Id} - T)^{-1}\|^{-1}$ λ_0

$$((\lambda_0 + h) \text{Id} - T)^{-1}$$

$$= (\lambda_0 \text{Id} - T + h \text{Id})^{-1}$$

$$= [(\lambda_0 \text{Id} - T)(\text{Id} + h(\lambda_0 \text{Id} - T)^{-1})]^{-1}$$

$$= (\text{Id} + h(\lambda_0 \text{Id} - T)^{-1})^{-1} (\lambda_0 \text{Id} - T)^{-1}$$

$$= \left[\sum_{k=0}^{\infty} (-1)^k h^k \cdot (\lambda_0 \text{Id} - T)^{-k} \right] (\lambda_0 \text{Id} - T)^{-1}$$

$$\Rightarrow \xi((\lambda_0 + h) \text{Id} - T)^{-1} = \sum_{k=0}^{\infty} (-1)^k \underbrace{\xi[(\lambda_0 \text{Id} - T)^{-k-1}]}_{\in \mathbb{C}} h^k$$

In other words,

"If $|h| < \frac{1}{\|(\lambda_0 \text{Id} - T)^{-1}\|}$, then

$$\varphi(\lambda_0 + h) = \sum_{k=0}^{\infty} (*) h^k$$

$\Rightarrow \varphi$ is hol. on $\rho(T) \subset \mathbb{C}$.

In fact

$$\varphi(\lambda) = \xi((\lambda \text{Id} - T)^{-1}) = \xi\left(\sum_{n \geq 0} T^n \lambda^{-n-1}\right)$$

$$= \sum_{n \geq 0} \frac{\xi(T^n)}{\lambda^{n+1}} \quad \| \xi \| \cdot \| T \| ^n = \| \xi \| \cdot \| T \| ^n$$

$$\Rightarrow |\varphi(\lambda)| \leq \sum_{n \geq 0} \frac{\|\xi\| \cdot \|T\|^n}{|\lambda|^{n+1}} = \sum_{n \geq 0} \frac{\|\xi\|}{|\lambda|} \left(\frac{\|T\|}{|\lambda|} \right)^n$$

$$= \frac{\|\xi\|}{|\lambda|} \cdot \frac{1}{1 - \frac{\|T\|}{|\lambda|}} \rightarrow 0 \quad (\lambda \rightarrow \infty)$$

$\Rightarrow$ If $\rho(T) = \mathbb{C}$, then by Liouville's theorem, $\varphi(\lambda) \equiv 0$

$$\Rightarrow \forall \xi \in (X)^*, \quad \xi((\lambda Id - T)^{-1}) = 0$$

$$\Rightarrow (\lambda Id - T)^{-1} = 0, \text{ a contradiction.} \quad \langle \xi, (\lambda Id - T)^{-1} \rangle = 0 \text{ for any } \xi \in X^*$$

Therefore $\sigma(T) \neq \emptyset$. □

Rmk. $r(T) = \max_{\lambda \in \sigma(T)} |\lambda|$



Thm. $\sigma(T) \setminus \{0\} = \sigma_p(T) \setminus \{0\}$

In other words, for $\lambda \neq 0$.

$$\lambda Id - T \text{ surjective} \iff \lambda Id - T \text{ injective}$$

$$\text{Im}(\lambda Id - T) = X \iff \ker(\lambda Id - T) = \{0\}$$

Lem. 1 • Recall for $\lambda \neq 0$, $\dim \ker(\lambda Id - T) < \infty$

$$\forall n \geq 1, \dim \ker(\lambda Id - T)^n < \infty$$

• $\text{Im}(\lambda Id - T)^n$ is closed. (omit.)

Lem. 2 $\exists n_0$ s.t. $\ker(\lambda Id - T)^{n_0} = \ker(\lambda Id - T)^{n_0+1}$

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 $\hookrightarrow \text{Im}(\lambda Id - T)^{n_0} = \text{Im}(\lambda Id - T)^{n_0+1}$

Proof. ①

- $K_n := \ker(\lambda Id - T)^n$
 K_n is closed. $\Rightarrow K_n$ is Banach
- $\text{Im} T|_{K_n} \subseteq K_n$ ($x \in K_n \Rightarrow (\lambda Id - T)^n T x = T(\lambda Id - T)^n x = 0$)
 $(K_n \text{ is } T\text{-invariant})$
- $(\lambda Id - T)^n = \lambda^n Id - S$ ($S = \lambda^{n-1} T \dots (-1)^n T^n$)
CLAIM. S is compact.

(Recall. $K(X)$ is a closed ideal of $L(X)$)

$$\lambda^n \neq 0 \Rightarrow \dim \ker(\lambda^n Id_{K_n} - S) < \infty. \quad \square$$

(Ref. Rudin. "Functional Analysis")

② FACT. Consider $T^*: X^* \rightarrow X^*$

$$T^* y^*(x) = y^*(Tx)$$

$$\langle x, T^* y^* \rangle = \langle Tx, y^* \rangle$$

$$[(x, T^* y) = (Tx, y)]$$

$$\| \dots \|_{T, T^*}^n \|_X = \text{Im}(\lambda Id - T)^n$$

$$\left(\ker (\lambda I - T^*)^n \right)^\perp = \overline{\text{Im}(\lambda I - T)^n}$$

annihilator "零化子"
 $= \text{Im}(\lambda I - T)^n$

Therefore, we only need to prove that
 $\exists n$ s.t. $K_n = K_{n+1}$

$$K_1 \subset K_2 \subset K_3 \subset \dots \subset K_n \subset K_{n+1} \subset \dots$$

Otherwise, $\forall n \geq 1, K_n \subsetneq K_{n+1}$

FACT. Take $x_n \in K_{n+1}, \|x_n\|=1$,
 with $\text{dist}(x_n, K_n) \geq \frac{1}{2}$

Consider $\{Tx_n\}$. By T compact,
 $\{Tx_n\}$ has a convergent subsequence.

$$\begin{aligned} \|Tx_m - Tx_n\| &= \|Tx_m - x_m + x_m - Tx_n\| \\ (\text{Assume } m > n, K_n \subset K_{m-1} \subsetneq K_m) & \quad \quad \quad \begin{array}{c} \|Tx_n\| \\ K_n \\ \downarrow \end{array} \\ &= \|x_m\| + \lambda^{-1} \underbrace{\|Tx_m - \lambda x_m - Tx_n\|}_{\substack{\| -(\lambda I - T)x_m \| \\ \uparrow \\ \text{dist}(x_m, K_{m-1}) \geq \frac{1}{2}}} \\ &\geq \frac{1}{2} \end{aligned}$$

which contradicts to $\{Tx_n\}$ has a
 convergent subsequence. $\square$

Take $\lambda < \delta(T)$ for

convergent sub sequence.

Proof of our main thm. Take $\lambda \in \sigma(T) \setminus \{0\}$
assume $\lambda \notin \sigma_p(T) \setminus \{0\}$
 $\Rightarrow \exists n_0$ s.t. $\dim(\lambda I - T)^{n_0} = \dim(\lambda I - T)^{n_0+1}$
 $\forall x, \exists y$ s.t. $(\lambda I - T)^{n_0} x = (\lambda I - T)^{n_0+1} y$
 $\lambda \notin \sigma_p(T) \Rightarrow \lambda I - T$ is injective, $= (\lambda I - T)^{n_0} (\lambda y - Ty)$

$$\Rightarrow x = \lambda y - Ty = (\lambda I - T)y$$

$\Rightarrow \lambda I - T$ is surjective. $\Rightarrow \lambda \notin \sigma(T)$,
a contradiction.

$$\sigma_p(T) \setminus \{0\} = \sigma(T) \setminus \{0\}.$$

In other words. If $\lambda \neq 0$, then

$\lambda I - T$ is surj. $\Leftrightarrow$ is inj. $\square$

Notation. Assume $\Omega \subset \mathbb{R}^n$, $x \in \Omega$.

Multi index Notation:

(a) $\alpha = (\alpha_1, \dots, \alpha_n)$ where α_i is a nonnegative integer, is called a multiindex with order $|\alpha| = \sum_{i=1}^n \alpha_i$

(b) α is a multiindex,

$$D^\alpha u(x) := \frac{\partial^{|\alpha|} u(x)}{\partial x_1^{\alpha_1} \cdots \partial x_n^{\alpha_n}} = \partial_{x_1}^{\alpha_1} \cdots \partial_{x_n}^{\alpha_n} u(x)$$

$$\alpha = (1, 1). \quad D^\alpha u(x) = \frac{\partial^2 u(x)}{\partial x_1 \partial x_2} = \partial_{x_1} \partial_{x_2} u(x)$$

(c) If k is a non-negative integer, then: $= u_{x_1 x_2}(x)$

$D^k u(x) := \{ D^\alpha u(x) \mid |\alpha| = k \}$ is the set of all k -order partial derivatives.

$$\# D^k u(x) = n^k$$

E.g. Gradient vect. $Du = (u_{x_1}, \dots, u_{x_n})$

Hessian matrix.

$$D^2 u = \begin{pmatrix} \frac{\partial^2 u}{\partial x_1^2} & \cdots & \frac{\partial^2 u}{\partial x_1 \partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial^2 u}{\partial x_n \partial x_1} & \cdots & \frac{\partial^2 u}{\partial x_n^2} \end{pmatrix}_{n \times n}$$

$$\Delta u = \text{Tr} D^2 u = \sum_{i=1}^n \frac{\partial^2 u}{\partial x_i^2}$$

(d) vector-valued functions

• $\vec{u}: \Omega \rightarrow \mathbb{R}^m$, $\vec{u} = \begin{pmatrix} u' \\ \vdots \\ u_m \end{pmatrix}$, we define

$$D^k \vec{u} = \{D^{\vec{\alpha}} \vec{u} : |\alpha| = k\} \text{ as before.}$$

• Gradient matrix (Jacobian matrix)

$$D \vec{u} = \left(\frac{\partial \vec{u}}{\partial x_1} \dots \frac{\partial \vec{u}}{\partial x_n} \right) = \begin{pmatrix} \frac{\partial u^1}{\partial x_1} & \dots & \frac{\partial u^1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial u^m}{\partial x_1} & \dots & \frac{\partial u^m}{\partial x_n} \end{pmatrix}_{m \times n}$$

• If $m=n$, we have:

$$\underset{\substack{\uparrow \\ \text{divergence}}}{\text{div} \vec{u}} = \text{Tr} D \vec{u} = \sum_{i=1}^n u^i_{x_i} = \text{"divergence of } \vec{u} \text{"}$$

$$\int_{\Omega} \text{div} \vec{u} \, dx = \int_{\partial \Omega} \vec{u} \cdot \nu \, dS$$

$$(\vec{u} \cdot d\vec{S})$$

Def. (Partial Differential Equation)

Fix an integer $k \geq 1$ and let $\Omega \subset \mathbb{R}^n$ open.

An expression of the form:

$$F(D^k u(x), D^{k-1} u(x), \dots, Du(x), u(x), x) = 0(x)$$

$$F(D^k u(x), D^{k-1} u(x), \dots, Du(x), u(x), x) = 0(x)$$

is called a k -th order PDE, where

$$F: \mathbb{R}^{n^k} \times \mathbb{R}^{n^{k-1}} \times \dots \times \mathbb{R}^n \times \mathbb{R} \times \Omega \rightarrow \mathbb{R}$$

is given, and $u: \Omega \rightarrow \mathbb{R}$ is unknown.

$\downarrow$
called a solution of (*)

Rmk. We solve the PDE if we find all u satisfying (*) (possibly among those satisfying certain boundary conditions on $\partial\Omega$)

In practice, we may not be able to solve some PDEs, instead, we only deduce the existence or other properties of solutions.

Def.

- The PDE (*) is called linear if it has the form:

$$\sum_{|\alpha| \leq k} \underline{a}_\alpha(x) D^\alpha u = \underline{f}(x)$$

The linear PDE is homogeneous if $f(x) \equiv 0$

- The PDE (*) is semilinear if it has the form:

$$\sum_{|\alpha| \leq k-1} \underline{a}_\alpha(x) D^\alpha u + \underline{a}_k(x) D^k u = \underline{f}(x)$$

the form:

$$\sum_{1 \leq |\alpha| \leq k} a_\alpha(x) D^\alpha u + a_0(D^{k+1}u, \dots, D_{n,n}u, x) = 0,$$

$\uparrow$ indep. of u $\uparrow$ indep. of $D^k u$

- The PDE (*) is quasi linear if it has the form:

$$\sum_{1 \leq |\alpha| \leq k} a_\alpha(D^{k+1}u, \dots, D_{n,n}u, x) D^\alpha u + a_0(D^{k+1}u, \dots, D_{n,n}u, x) = 0$$

- The PDE (*) is called fully-nonlinear if it depends nonlinearly upon the highest order derivatives $D^k u$.

Examples

The list of many specific PDE of interest in current research.

a. Linear

* Laplace's eq. $\Delta u = 0$

• Helmholtz's eq. $\Delta u + \lambda u = 0$

* Linear transport eq. $u_t + \sum_{i=1}^n b_i u_{x_i} = 0$ or

• Liouville's eq. $u_t + P(\vec{b} \cdot \nabla u) = 0$ $u_t + \vec{b} \cdot \nabla u = 0$

- Liouville's eq. $u_t + P(\vec{b} \cdot \nabla)u = 0$

$$u_t + b \cdot \nabla u = 0$$

- ★ Heat eq. $u_t = \Delta u$

- Schrödinger's eq. $i \partial_t u = \Delta u$

- Kolmogorov's eq.

$$u_t = \sum_{i,j=1}^n a^{ij} u_{x_i x_j} - \sum_{i=1}^n b^i u_{x_i}$$

- Fokker-Planck's eq.

$$u_t = \sum_{i,j=1}^n (a^{ij} u)_{x_i x_j} - \sum_{i=1}^n (b^i u)_{x_i}$$

- ★ Wave eq. $u_{tt} = \Delta u$

$$\left[\text{General Wave eq. } u_{tt} = \sum_{i,j=1}^n a^{ij} u_{x_i x_j} - \sum_{i=1}^n b^i u_{x_i} \right]$$

- Airy's eq. $u_t + u_{xxx} = 0$

- Beam eq. $u_t + u_{xxxx} = 0$

b. Nonlinear

- Nonlinear Poisson eq. $\Delta u = f(u)$

- p-Laplacian eq. $\operatorname{div} \left(\frac{|Du|^{p-2}}{p} Du \right) = 0$

$$Du = \sqrt{\sum_{i=1}^n |u_{x_i}|^2}$$

$$Du = \sqrt{\sum_{i=1}^n |u_{x_i}|^2}$$

- Minimal-Surface eq.

$$\operatorname{div} \left(\frac{Du}{\sqrt{1+(Du)^2}} \right) = 0$$

- Monge-Ampère eq.

$$\det(D^2u) = f(u)$$

- Hamilton-Jacobi eq.

$$u_t + \underline{H}(Du, x) = 0$$

- KdV eq. $u_t + uu_x + u_{xxx} = 0$

C. linear and nonlinear systems.

- Maxwell's eq.s

$$\begin{cases} E_t = \operatorname{curl} B \\ B_t = -\operatorname{curl} E_t \\ \operatorname{curl} B = \operatorname{div} E = 0 \end{cases}$$

- Navier-Stokes eq.s

(for incompressible, viscous fluid)

$$\begin{cases} \vec{u}_t = \Delta \vec{u} - D_p - \vec{u} \cdot D \vec{u} \\ \operatorname{div} \vec{u} = 0 \end{cases}$$

Next time : transport eq.